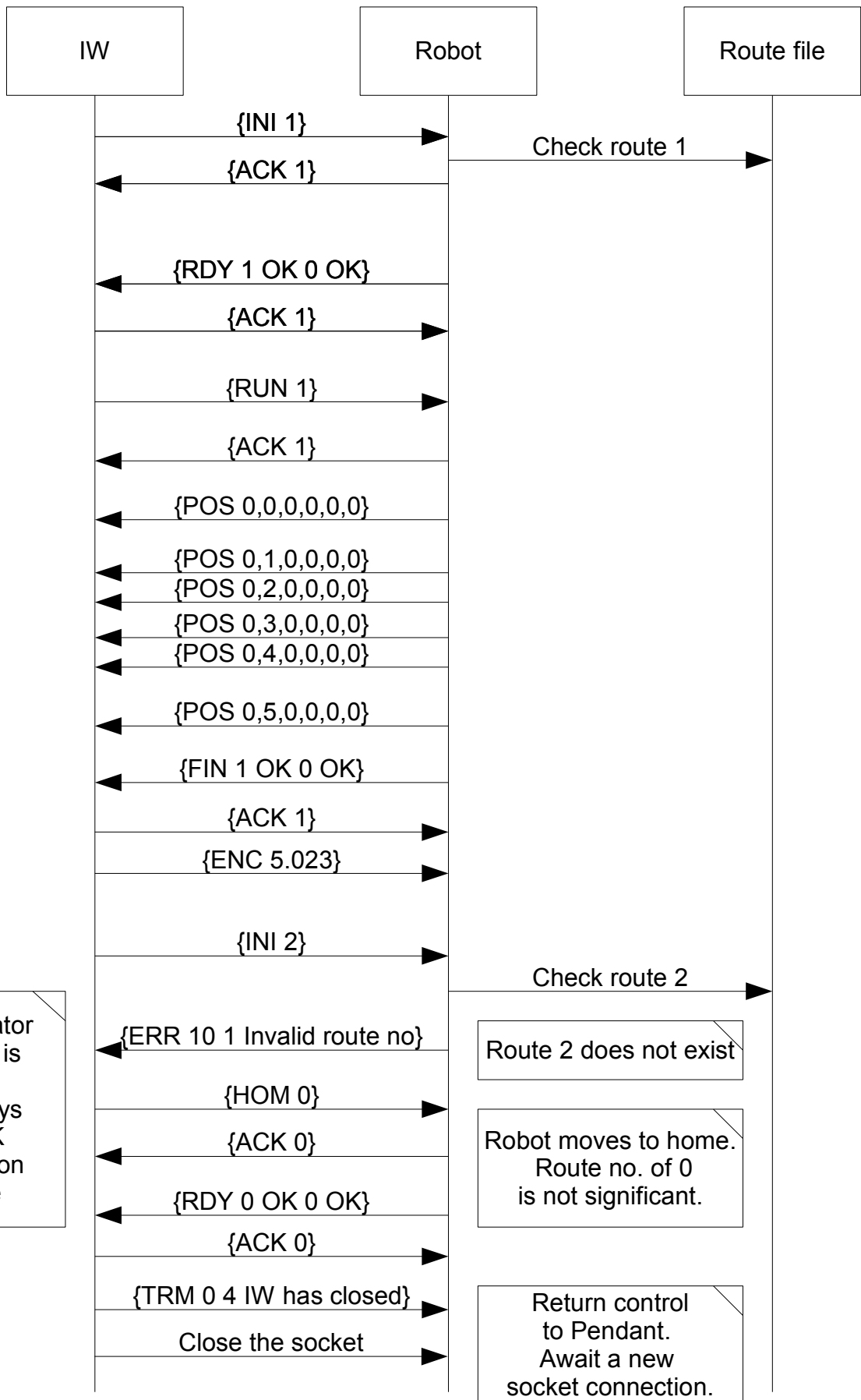


End of Inspection



Inform operator
entire scan is
complete.
Operator says
scan is OK
Exit inspection
sequence

Route 2 does not exist

Robot moves to home.
Route no. of 0
is not significant.

Return control
to Pendant.
Await a new
socket connection.